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Yoshihara, K.; Hoh, T.;
Robotics and Automation, 1988. Proceedings., 1988 IEEE International Conference on
24-29 April 1988 Page(s):1469 - 1473 vol.3
IEEE CNF
- 2. When physics rules robotics: scaling issues in the design of robots and robotic applications**
Siegel, M.;
Instrumentation & Measurement Magazine, IEEE
Volume 7, Issue 3, Sept. 2004 Page(s):52 - 59
IEEE JNL
- 3. Study on a Kind of Wall Cleaning Robot**
Xueshan Gao; Kikuchi, K.;
Robotics and Biomimetics, 2004. ROBIO 2004. IEEE International Conference on
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1. Mobile robot area filling

Bing-Yung Chee; Lang, S.Y.T.;
Advanced Intelligent Mechatronics '97., IEEE/ASME International Conference on
16-20 June 1997 Page(s):106
IEEE CNF

2. Region filling operations for mobile robot using computer graphics

Huang, Y.; Cao, Z.; Hall, E.;
Robotics and Automation. Proceedings. 1986 IEEE International Conference on
Volume 3, Apr 1986 Page(s):1607 - 1614
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